

[24]

$$\begin{aligned} \vec{a} &= 5\hat{i} + 4\hat{j} - 6\hat{k} \\ -\vec{b} &= 2\hat{i} - 2\hat{j} - 3\hat{k} \\ +\vec{c} &= 4\hat{i} + 3\hat{j} + 2\hat{k} \\ \hline \vec{r} &= 11\hat{i} + 5\hat{j} - 7\hat{k} \end{aligned}$$

$$|\vec{r}| = \sqrt{121 + 25 + 49} = \sqrt{195} \approx 14$$

$$b) \cos \theta = \frac{\vec{r} \cdot \hat{k}}{|\vec{r}| |\hat{k}|} = \frac{-7}{14} \Rightarrow \theta = \cos^{-1}(-\frac{1}{2}) \Rightarrow \theta = 120^\circ$$

$$[36] \vec{a} = 3\hat{i} + 3\hat{j} - 3\hat{k}$$

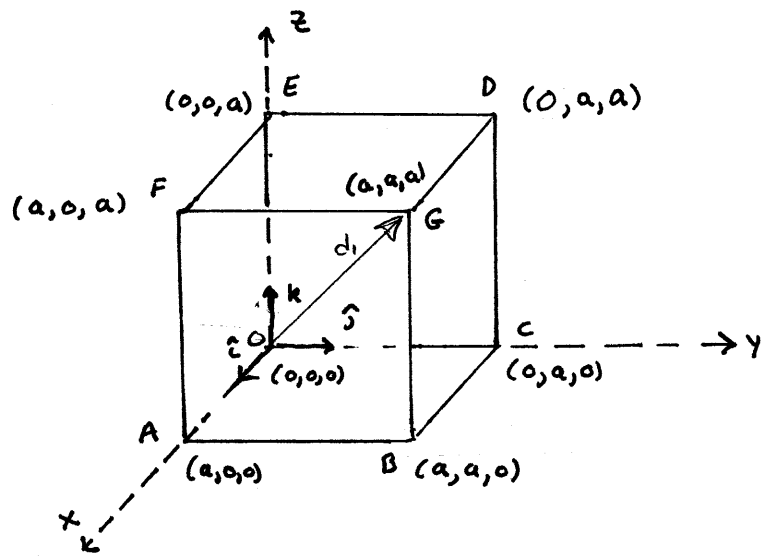
$$\vec{b} = 2\hat{i} + \hat{j} + 3\hat{k}$$

$$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$$

$$\cos \theta = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}| |\vec{b}|} = \frac{6 + 3 - 9}{\sqrt{27} \sqrt{14}} = 0$$

$$\text{Then } \theta = 90^\circ$$

[37]



a) diagonal

$$\vec{OG} = a\hat{i} + a\hat{j} + a\hat{k}$$

$$\vec{EB} = (a-0)\hat{i} + (a-0)\hat{j} + (0-a)\hat{k} = a\hat{i} + a\hat{j} - a\hat{k}$$

$$\vec{CF} = (a-0)\hat{i} + (0-a)\hat{j} + (a-0)\hat{k} = a\hat{i} - a\hat{j} + a\hat{k}$$

$$\vec{DA} = (0-a)\hat{i} + (0-a)\hat{j} + (0-a)\hat{k} = a\hat{i} - a\hat{j} - a\hat{k}$$

} Negatives of these correct, too. direction is arbitrary.

b) compute angle of \vec{OG} with z-axis. By symmetry, this answers all.

$$\cos \theta = \frac{\vec{OG} \cdot a\hat{k}}{|\vec{OG}| |a\hat{k}|} = \frac{a\hat{k} \cdot a\hat{k}}{\sqrt{a^2+a^2+a^2} a} = \frac{a^2}{a^2\sqrt{3}} = \frac{1}{\sqrt{3}}$$

$$\text{then } \theta = \cos^{-1}\left(\frac{1}{\sqrt{3}}\right) \approx 0.96 \text{ RAD} \approx 54.7^\circ \text{ ANS}$$

c) LEN DIAG. use \vec{OG} and others are EQ to it

$$|\vec{OG}| = \sqrt{a^2+a^2+a^2} = a\sqrt{3} \text{ ANS}$$

d) PICK \vec{OG} and \vec{EB} .

$$\cos \theta = \frac{\vec{OG} \cdot \vec{EB}}{|\vec{OG}| |\vec{EB}|} = \frac{a^2+a^2-a^2}{3a^2} = \frac{a^2}{3a^2} = \frac{1}{3}$$

$$\text{Then } \theta = \cos^{-1}\left(\frac{1}{3}\right) \approx 1.2 \text{ RAD} \approx 70.5^\circ \text{ ANS}$$